

FindMine gGmbH and Project findmine

Public Presentation 07/2025



findmine
FindMine gGmbH – Explosives search with the help of UAVs.



Urs Endress Foundation

Mission

Make the world safer by helping to get rid of mines and unexploded ordnances with latest technologies.

Promotion of projects making humanitarian minesweeping faster, safer, and cheaper by new technologies especially the use of UAV (Unmanned Airborne Vehicle) with high performance sensors.

Foundation Board:
Urs Endress and
6 board members



Motivation

APM cost:

- Production: 3\$ - 5\$
- Clearance: 500\$ - 1000\$.

URS ENDRESS
foundation.

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- > 100 Mio buried mines.
- **Dramatical rise of UXO contamination in quantity and quality from ongoing and rising conflicts of the last few years.**
- Consequences:
 - Deaths, injuries.
 - Blocked Humanitarian aid.
 - Refugees, Starvation.
 - Impeding of development and reconstruction.

Area Reduction:

- Up to 500 false alarms for one mine.
- Just 10% of suspected areas contain hazardous objects.
- Clearance cost: > 500K\$/km²

Image:  FSD FONDATION SUISSE DE DÉMINAGE

Findmine Research Basis

2015

Feasibility study on UAV-based automated detection and localization of buried landmines

2016 – 2022

Intensive research on ground penetrating synthetic aperture radar (GPSAR) mounted on an UAV flying autonomously a few meters above ground (< 6m)

2019 – 2023

Complementary research on UAV-carried metal-detection and vegetation and soil-effects in low height (<1m) GPR

2024

New GPSAR evaluation algorithms

Since 2025 mainly development work.

INFO and Publications www.findmine.org

Research partners:

- Technische Hochschule Ulm (IAF)
- Universität Stuttgart (IFR, TTI)
- Universität Ulm (MWT)
- ETH Zürich (IRIS)
- Fachhochschule Nordwestschweiz (FHNW)
- Endress+Hauser Technologieentwicklung
- École Polytechnique Fédérale de Lausanne (EPFL)



FindMine gGmbH

- Startup-like company
- Non-profit
- 8 employees (6.5 40h FTEs)
- UAV-based explosive hazard detection systems
- Bridging research results to useable systems
- 100% shareholder

Urs Endress Foundation

- Operational since July 2022
- First products planned for end of this year (2025)



FindMine gGmbH
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Phone: +49 7303 163990
Trade register Memmingen: HRB19916
CEO Dr. Winfried Mayer



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Location: Illertissen, Bavaria,
Germany; 30km south of Ulm.

Projects

FM-GPSAR

Ground Penetrating
Synthetic Aperture Radar



- Large Area Scan
- Non-Technical Survey
- Demining Quality Scan

FM-METAL

Multi-Mode Metal
Detector



- Confirmation for GPSAR
- False-alarm reduction
- Spot Measurements
- Demining Quality Check

FM-LSCAN

Linear Scanning
Radar



- Path and Road-Side scanning
- Areas with fly-over restrictions
- Shadowed areas

FM-TEST

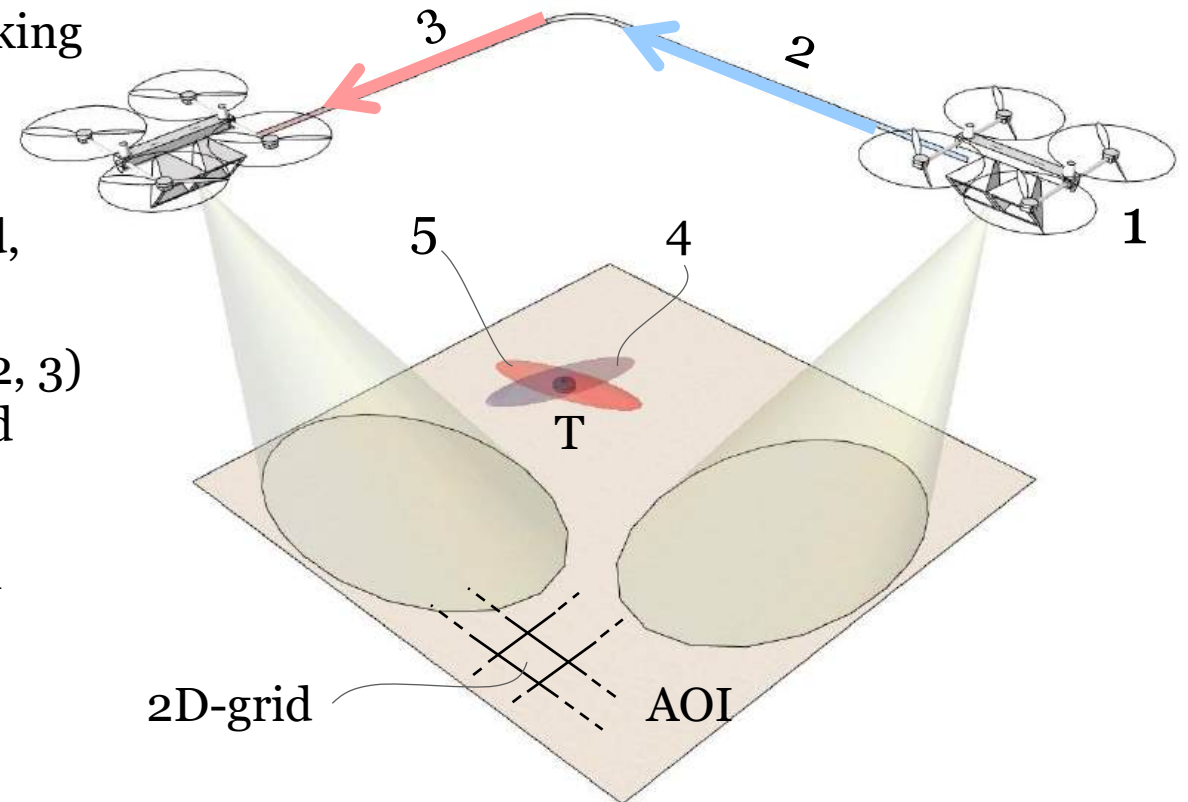
Activities and Facilities
for Test and Validation



- Testfields
- Dummies
- Reference conditions
- Data Collection

FM-GPSAR Principle

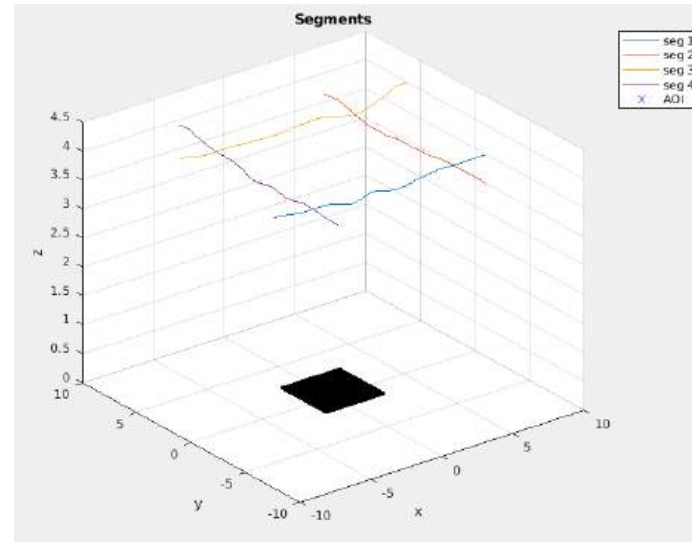
- UAS with broad-band ground penetrating radar (1)
 - Rectangular resolution (2D-grid) of the area of interest (AOI)
 - in one dimension by range resolution and side-looking
 - in second dimension by SAR-combination along a linear flight section (2)
- Targets (T) cause high intensity spots (4) in the 2D-grid, but blurred, spread and ambiguous by soil refraction
- Combining the spots (4, 5) from different flight paths (2, 3) by special processing concentrates detection results and provides depth resolution
- GPSAR-Results: Layered radar images of the upper soil with high-intensity spots from



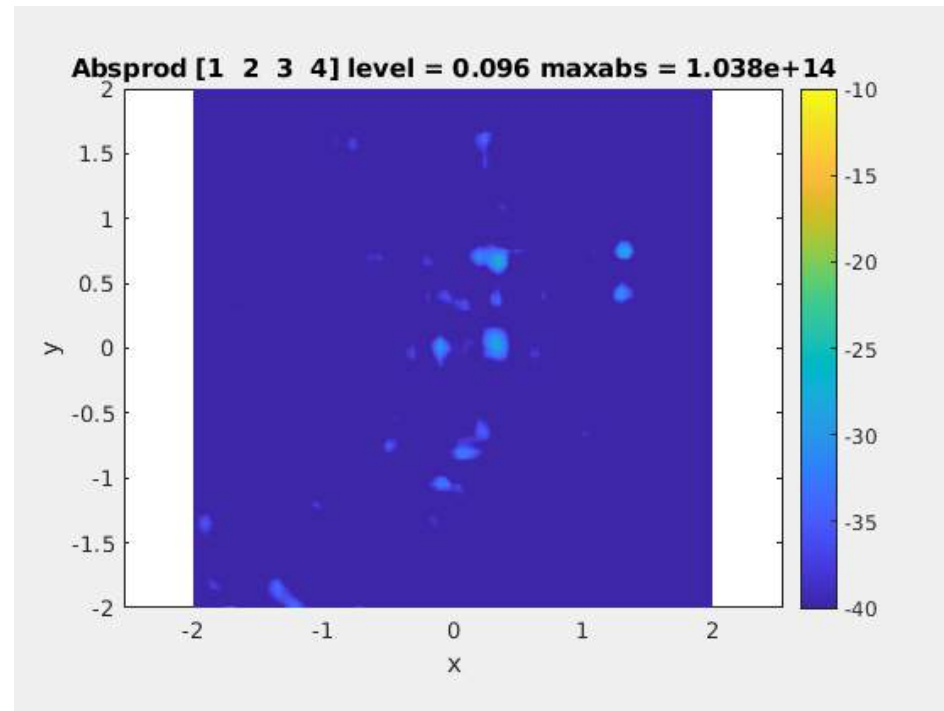
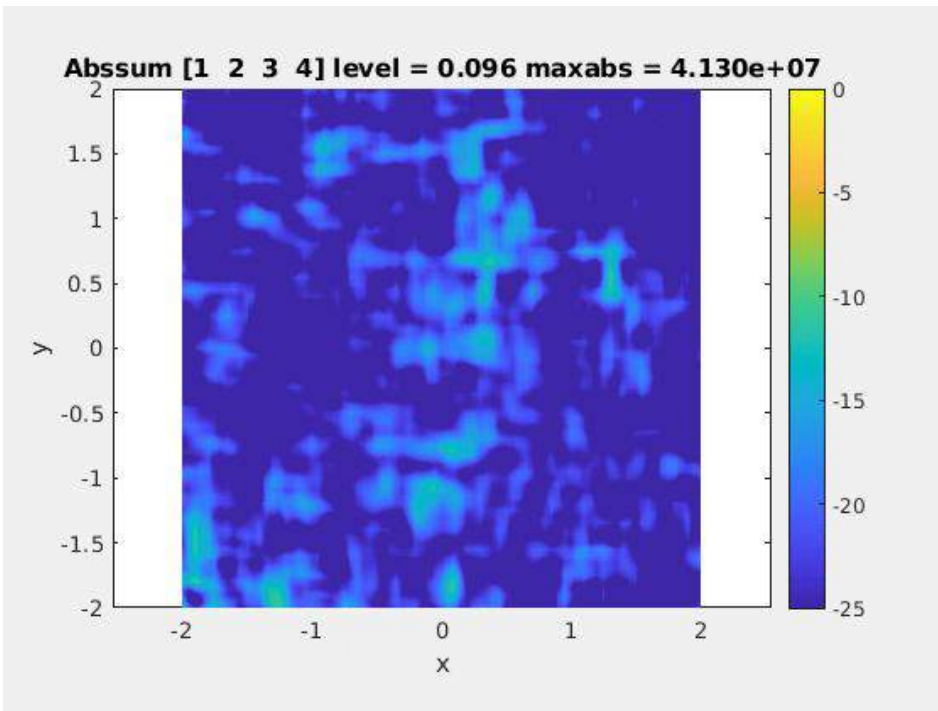
~ Microwave Tomography

FM-GPSAR Results

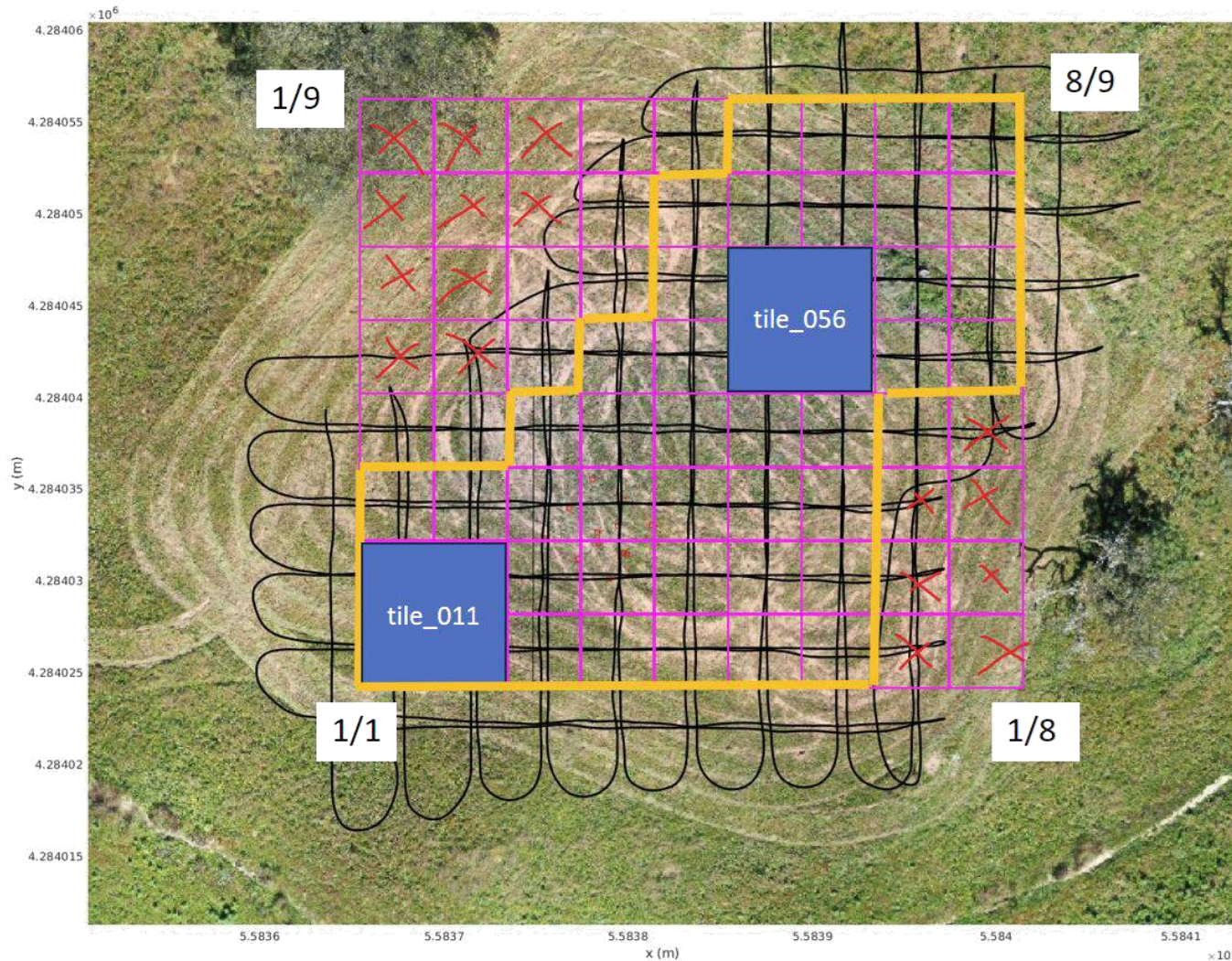
3 metal APM-dummies
buried 3-5cm below low
grass in natural terrain



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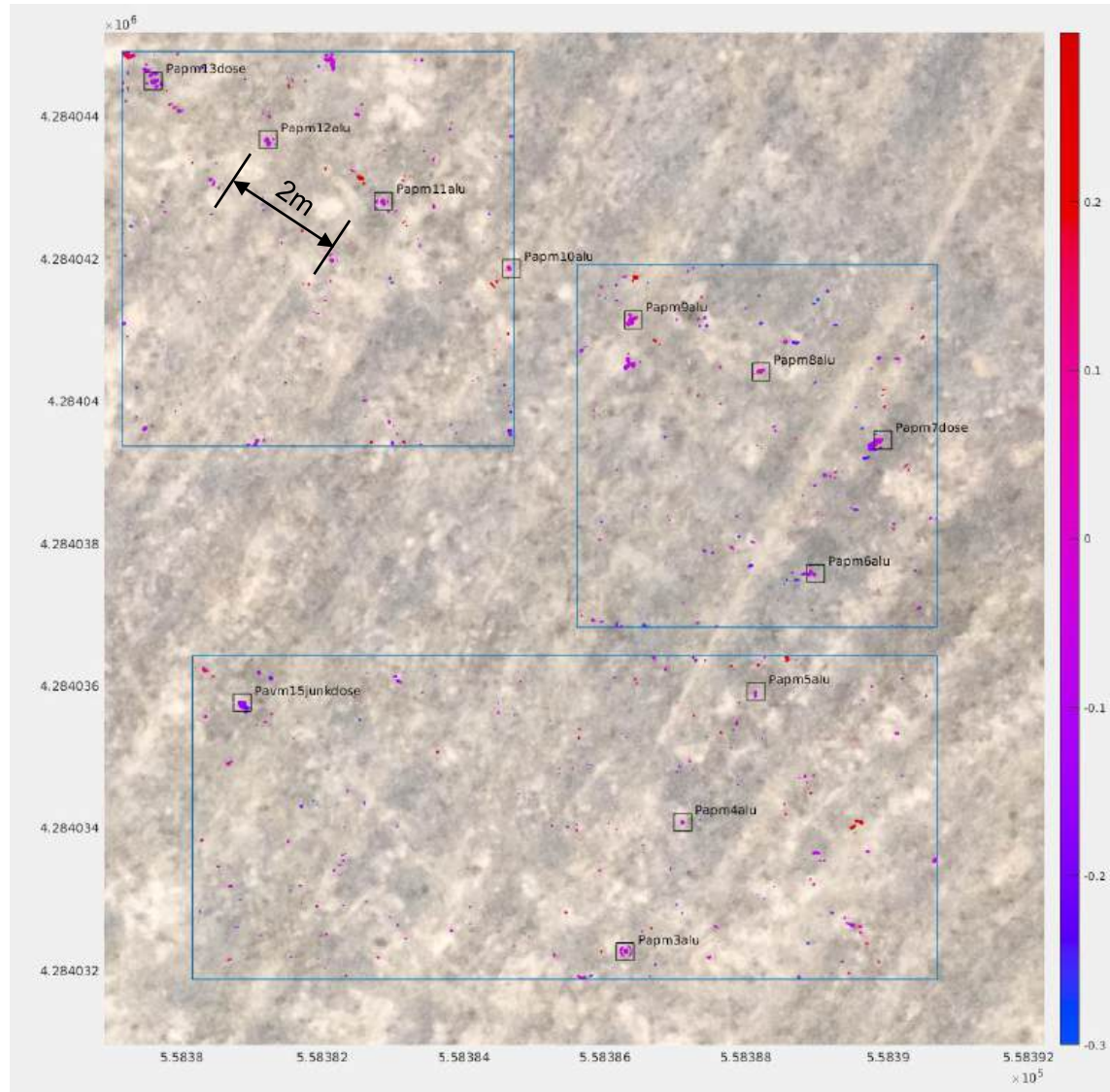


FM-GPSAR System

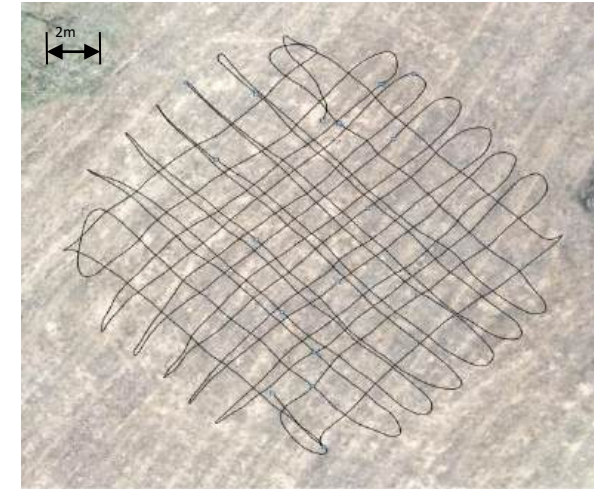


- GPSAR offline processing requires powerful and GPU-supported computing system
- Search flight speed up to 2000m²/h
- Processing time equals search flight time
- Processing depending on resolution
- Typical voxel resolution horizontal 5cm, vertical 1cm

FM-GPSAR Test-Results



- Successful results in natural terrain with dry vegetation
- Dummies buried 4 moths before measurement
- Cross-meander flight paths
- Despite strong winds and high temperature

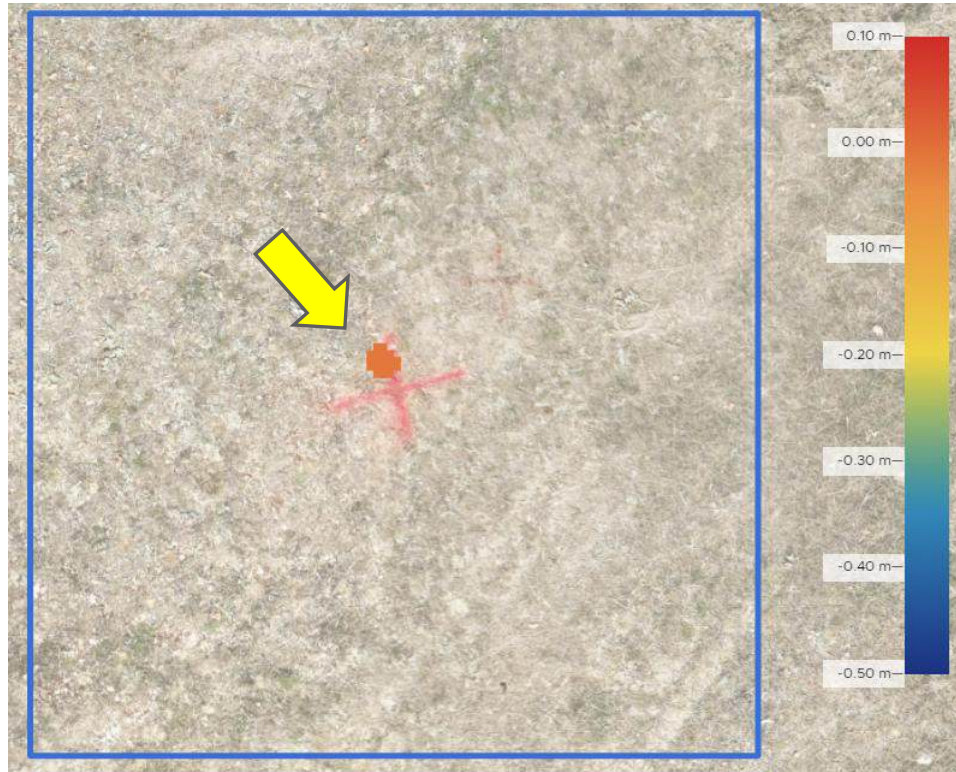


FM-GPSAR Test-Results

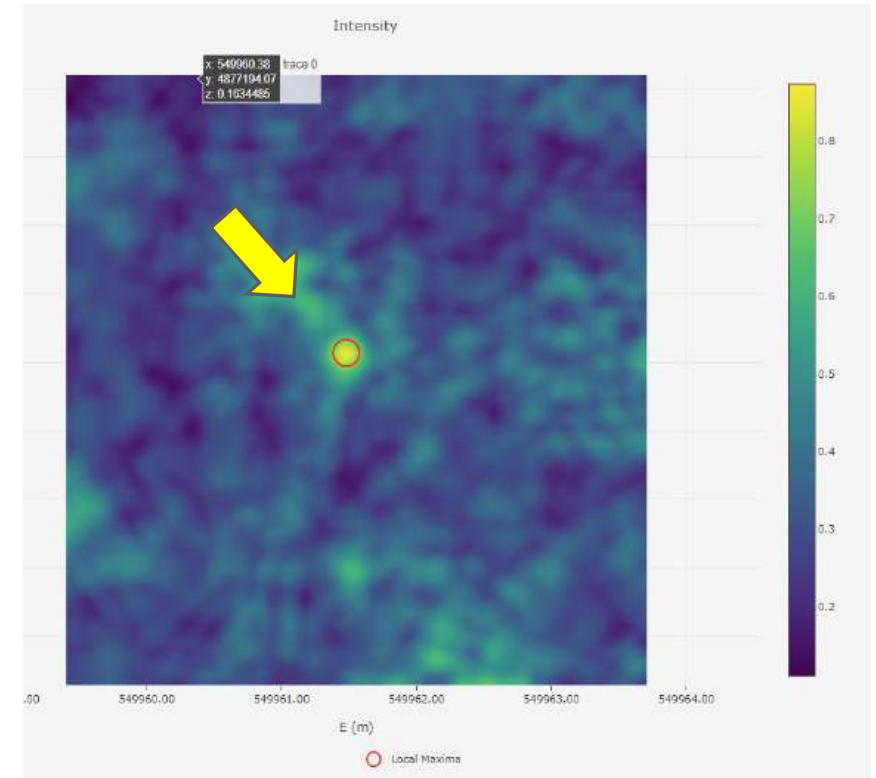
Detection of real defused mines in CTRO test-field Benkovac



Minetype and close photograph of the the 1m² containing it



Detection diagram from 4m x 4m evaluated with orthophoto as background



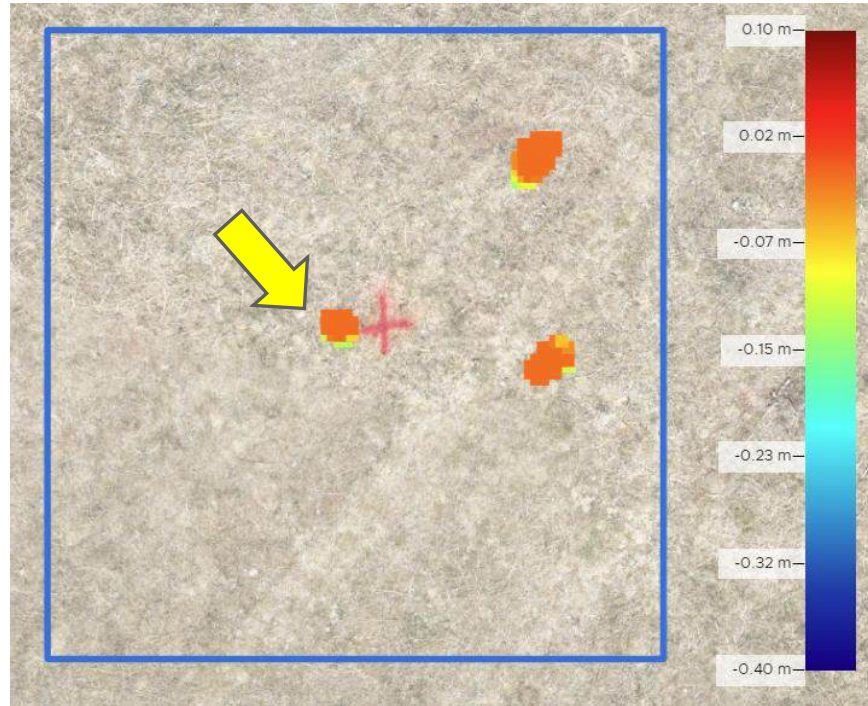
Intensity diagram for 0.15m depth

FM-GPSAR Test-Results

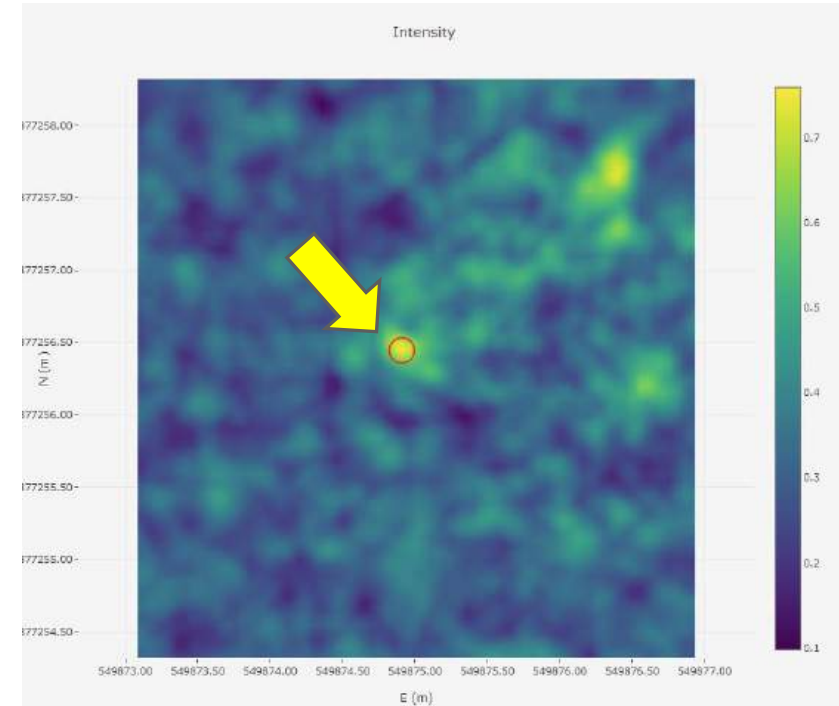
Detection of real defused mines in CTRO test-field Benkovac



Object and photograph of the 1m² containing it.



Detection diagram from 4m x 4m evaluated.



Intensity diagram for 0.2m depth.

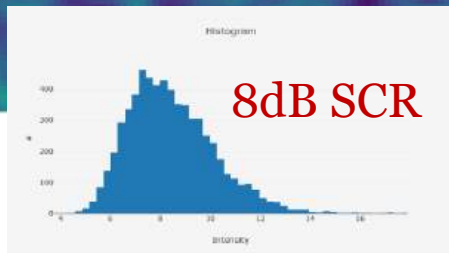
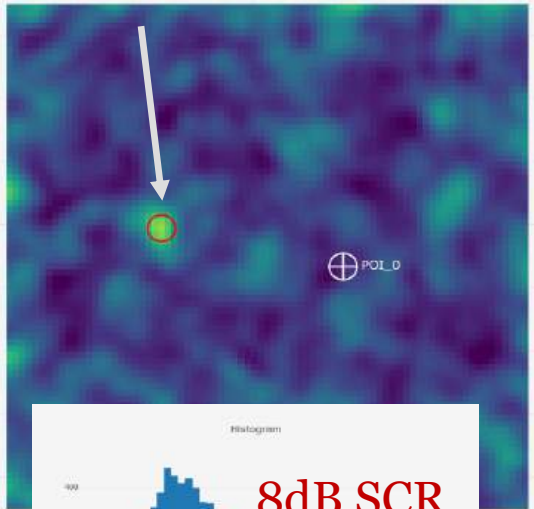
FM-GPSAR Test-Results

Detection of surface laid AVM and APM-dummies hidden in vegetation

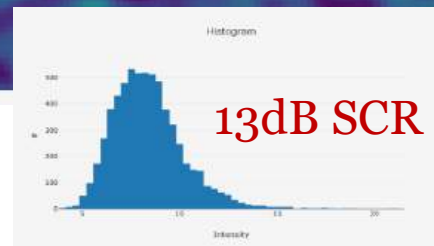
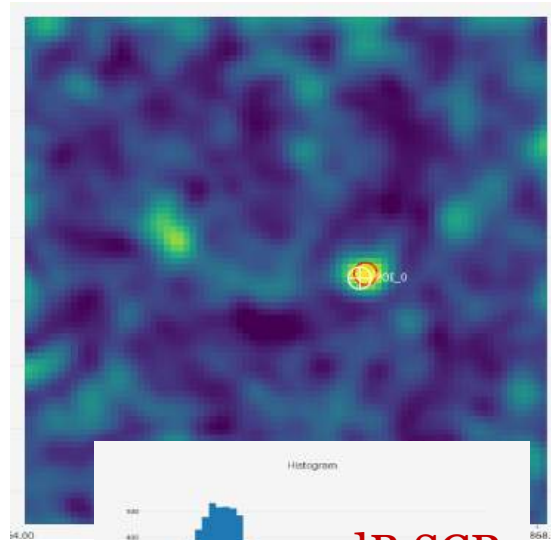
Empty area



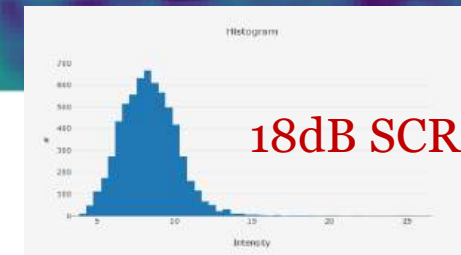
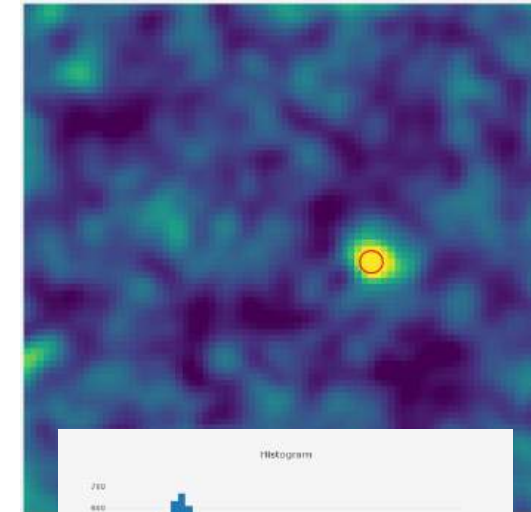
ants'
hill



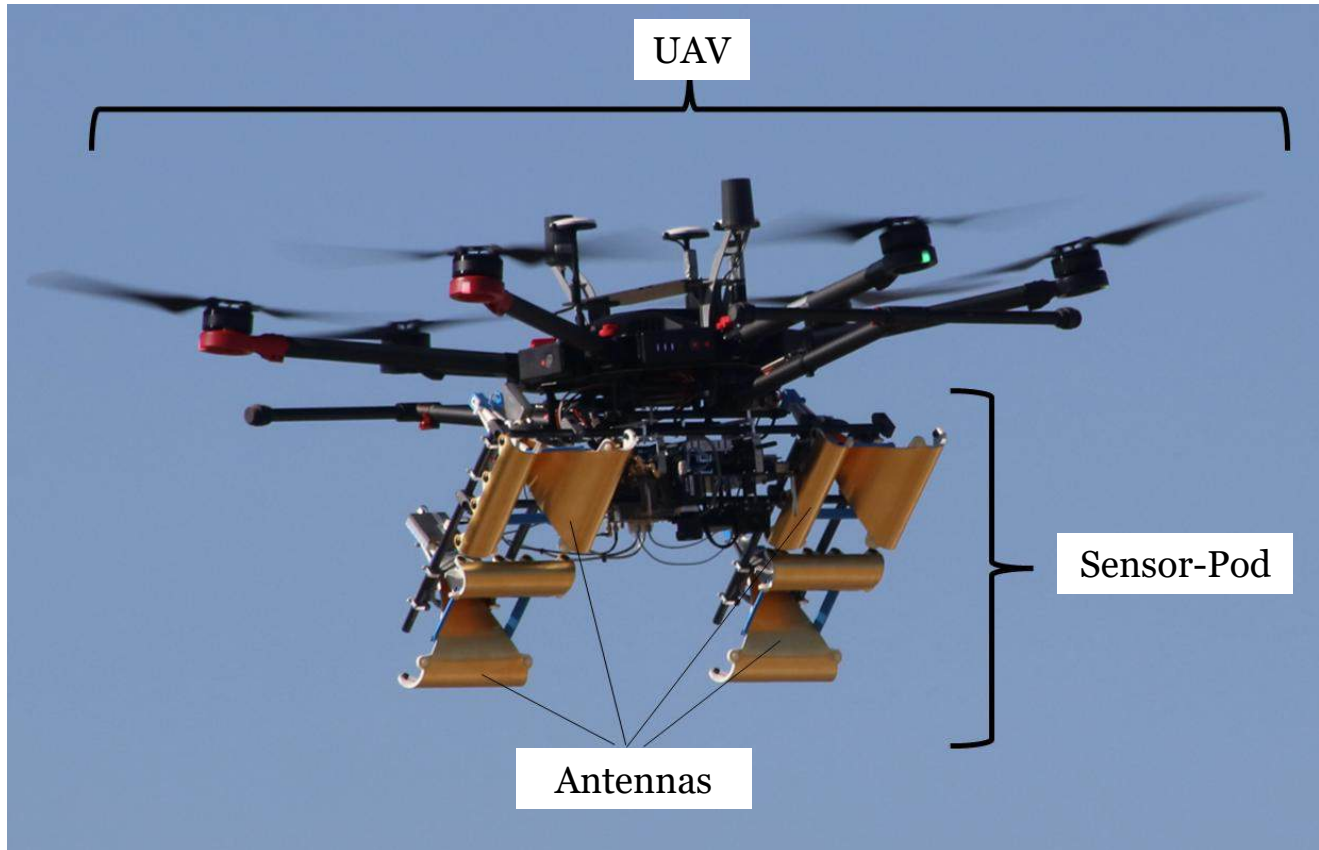
with PMR3 dummy



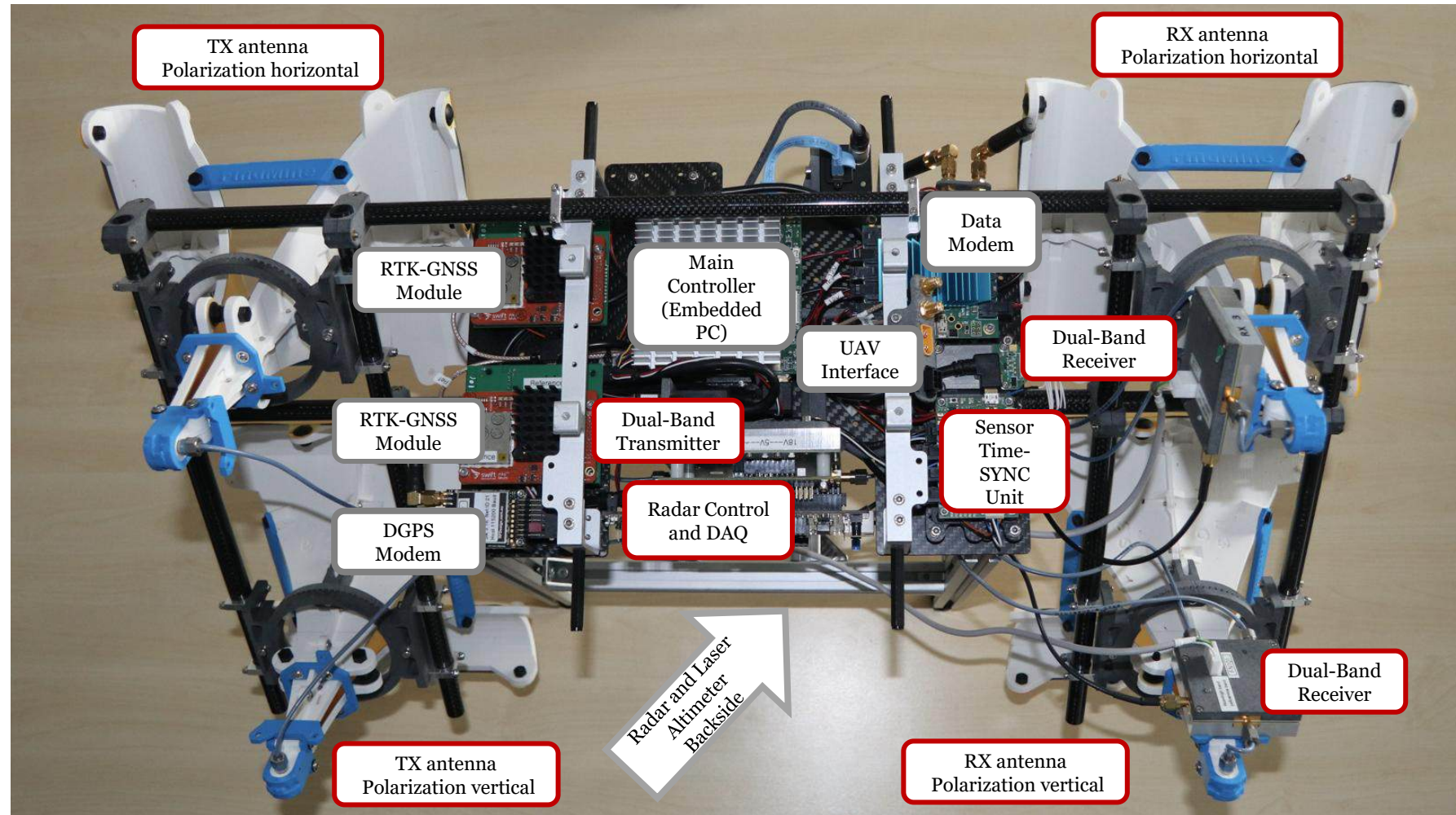
with TMRP-6 Dummy



FM-GPSAR Hardware



FM-GPSAR Sensor-Pod



in-house
design

purchased
part

Available
4 operating
2 experimental
1 spare-parts

FM-METAL Concept

- Multi-Layer and Multi-Mode Detector with several parallel channels
- Low false alarm rate and fast evaluation
- Light-weight for UAV-operation
- Metal content confirmation for locations with GPSAR-detections from area-scan
- Requires low altitude precision RTK-based flights
 - Low area throughput



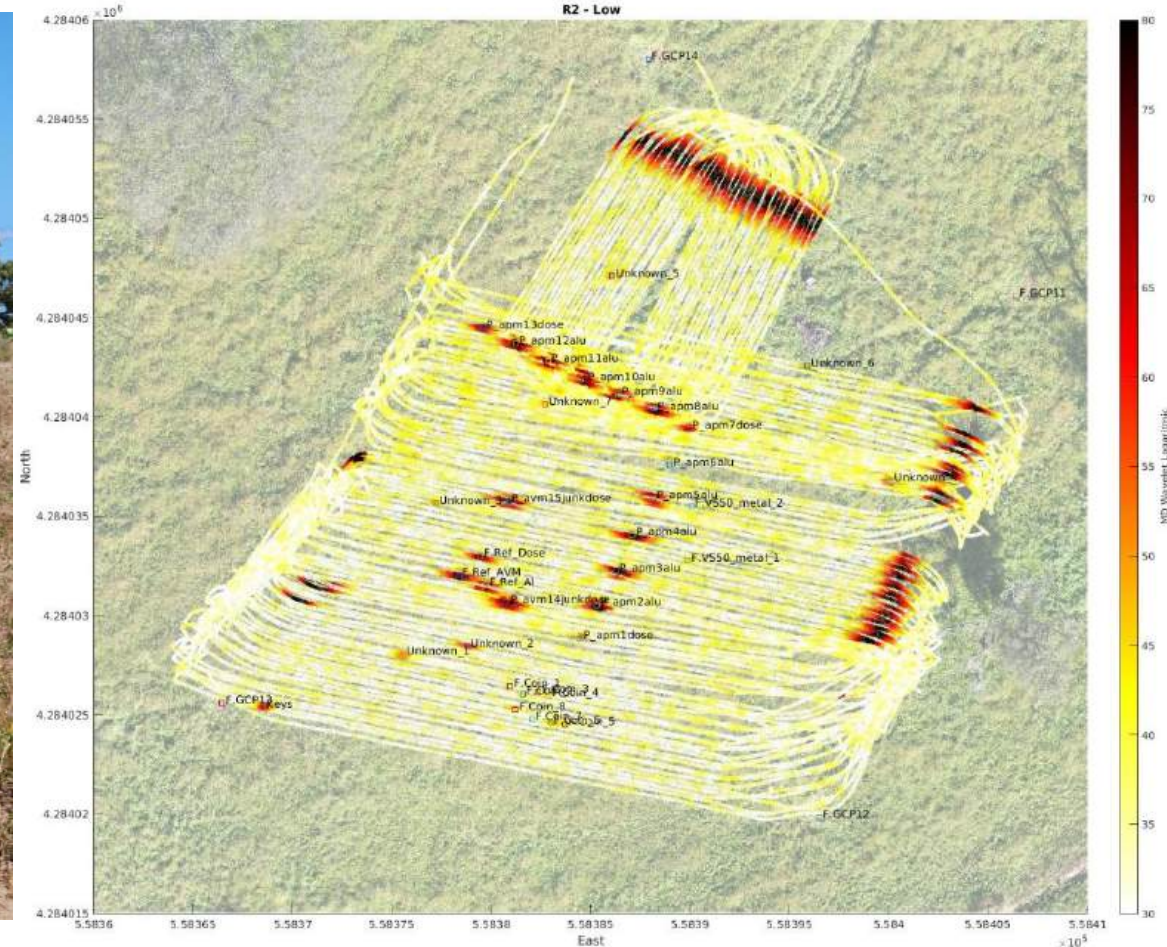
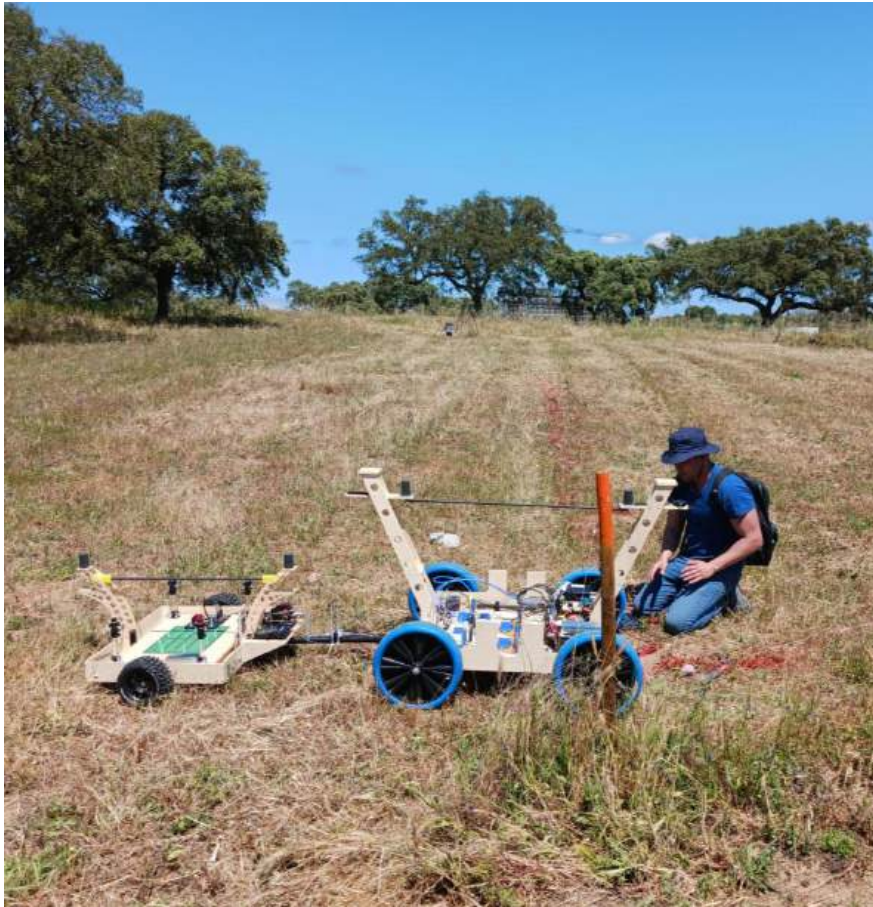
FM-METAL Sensor

- Multilayer PCB-based sensor
 - Vibration insensitive
 - Simple calibration and adjustment
 - Different coils in one multi-layer PCB
 - Low-cost and high-quality
- Maximum use of common electronics for radar and metal sensors
- 2 frequencies for metal type distinction

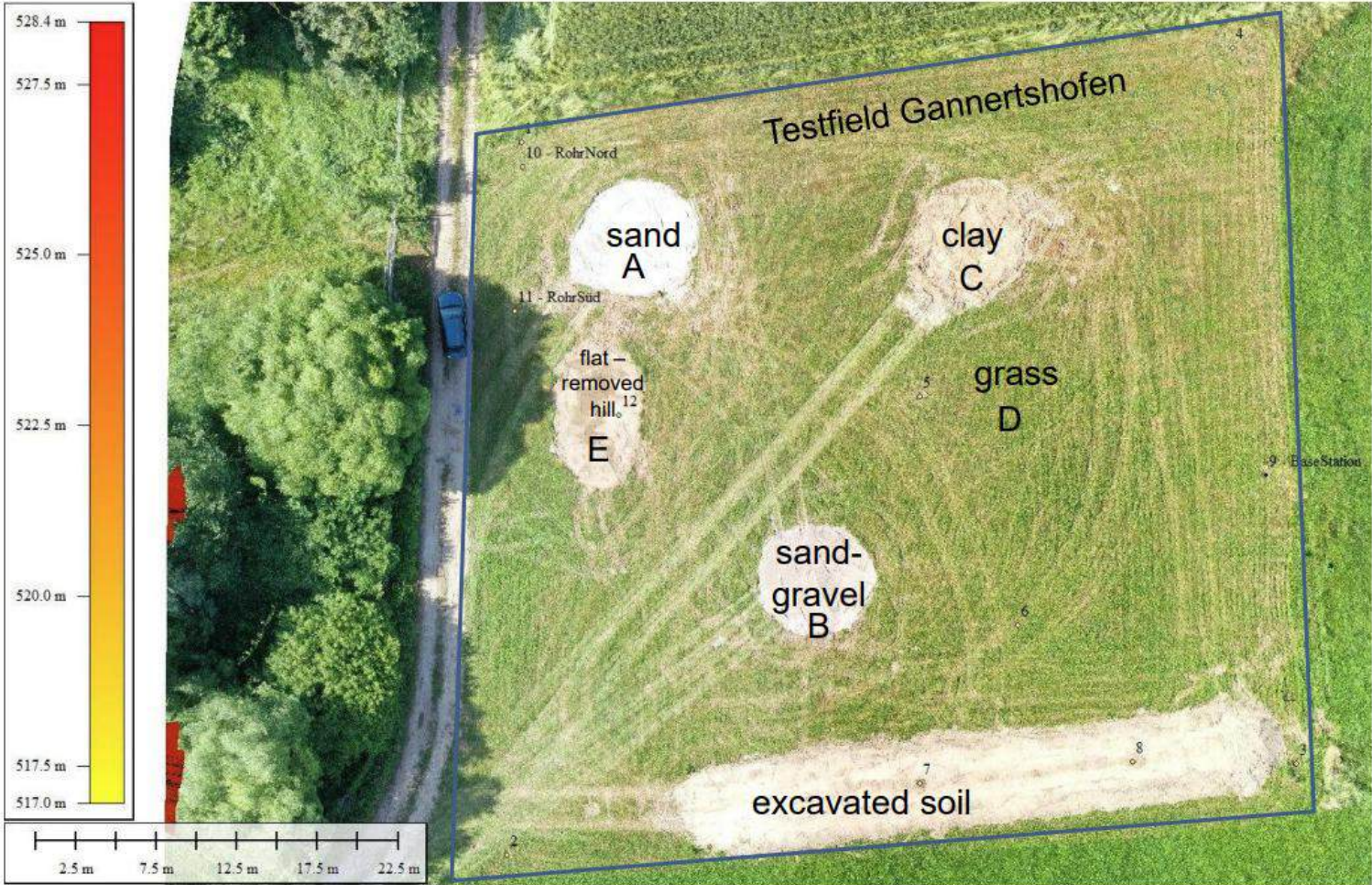


FM-METAL Results

Rover as test platform for sensor-optimization.



FM-TEST Gannertshofen DE



Aerial images taken 21.06.2021 by 'DJI Mavic Pro 2', Imagemap made by 'Pix4D'



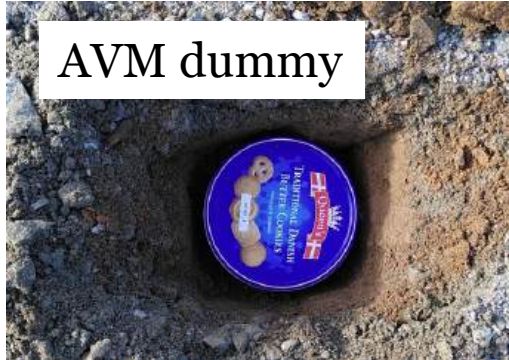
APM Simulants



More than 100 buried simulants.

FM-TEST

Freixo Portugal



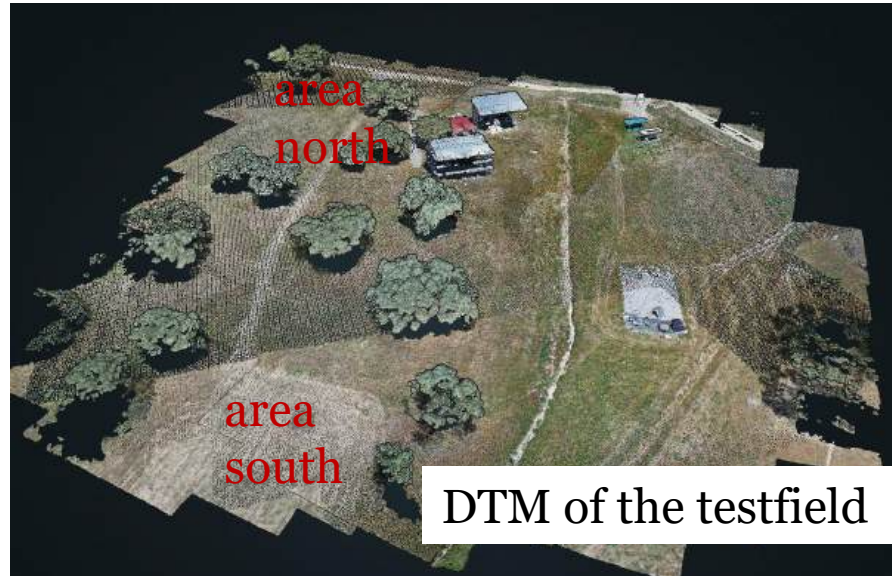
AVM dummy



GPSAR in operation



dirt road scenery



DTM of the testfield



Ground control



logistics

**Contact for questions and ideas on
findmine R&D activities, results,
technological cooperation:**

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www.findmine.org**

**Contact for general questions on
humanitarian demining, and if you are
interested to support us:**

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Further interest ?